

Lockheed Martin Low-Cost F-35 Simulator

Senior Design Team 514



Will Rickles



Meet the Team



Jonah Gibbons
*Electrical & Manufacturing
Engineer*



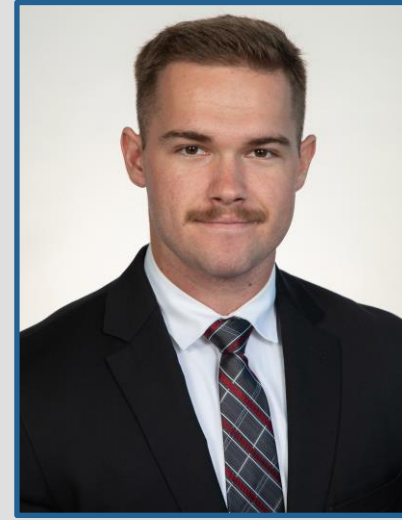
Laiken Kinsey
*Test Engineer & Project
Manager*



Francisco Lopez
*Mechanical & Product
Design Engineer*



Branden Pacer
*Mechanical Engineer &
Gimbal Design*



Will Rickles
Mechatronics Engineer



Emelia Rodriguez
*Purchasing &
Research Engineer*

Will Rickles



Sponsor and Advisor



Andrew Filiault
Mechanical Engineer, B.S.
JSF F-35 Pilot Training and
Training Infrastructure Systems



FAMU-FSU
College of Engineering

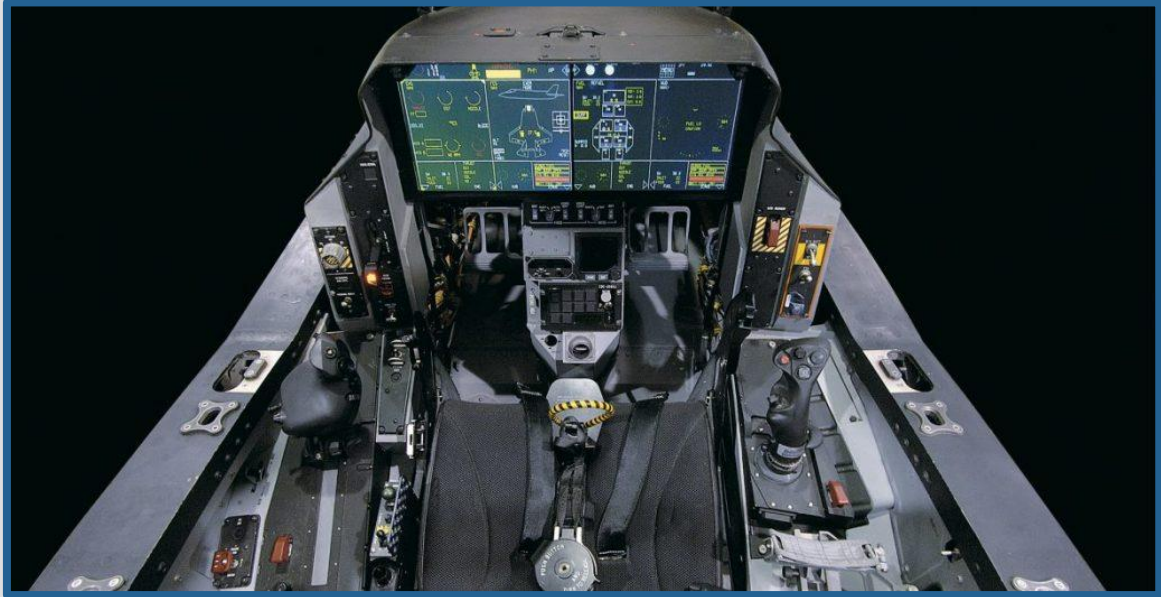


Brandon Krick
Mechanical Engineer, Ph.D.
Associate Professor

Will Rickles



Project Objective



The objective of this project is to create F-35 flight controls that integrate with Lockheed Martin's simulator software to be used in the pilot training program.

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3D Printed Cockpit and Desktop Simulator

- ✈️ Pilots train in simulators to develop muscle memory and learn the unique operating procedures of the aircraft



Full Scale Simulator



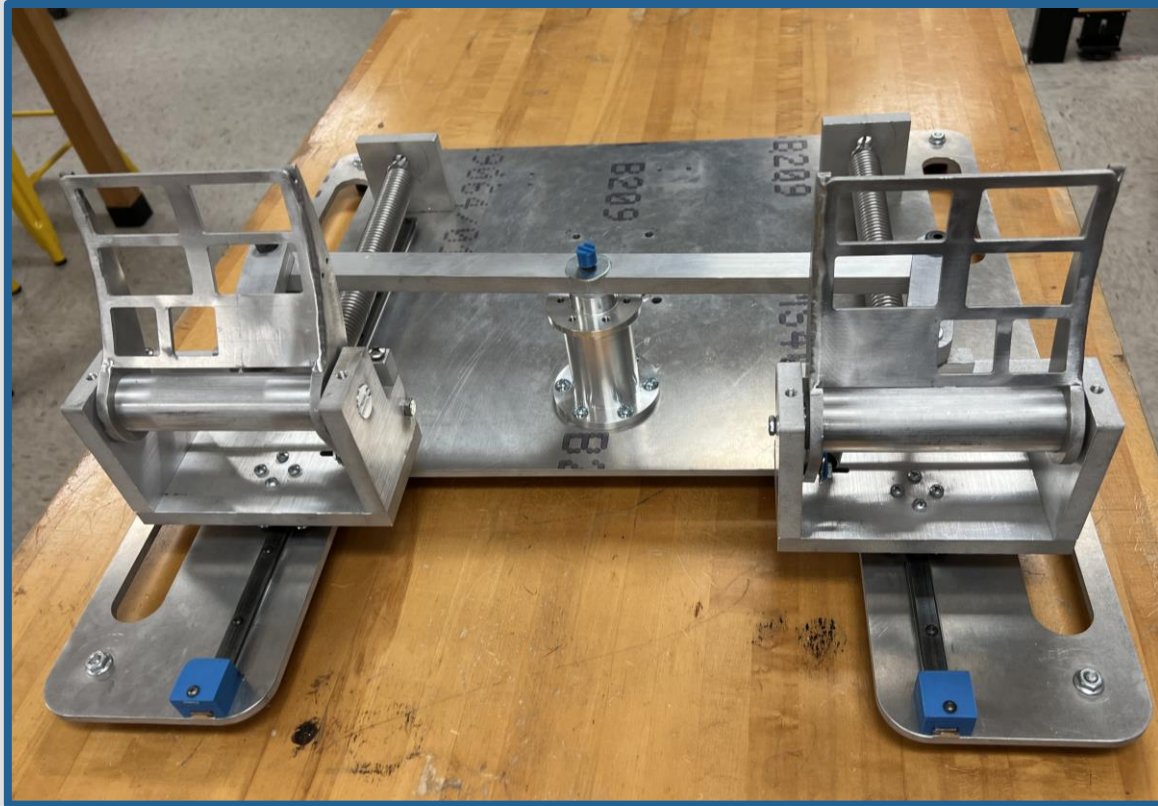
3D Printed Cockpit



Desktop Simulator

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Rudder Pedal System

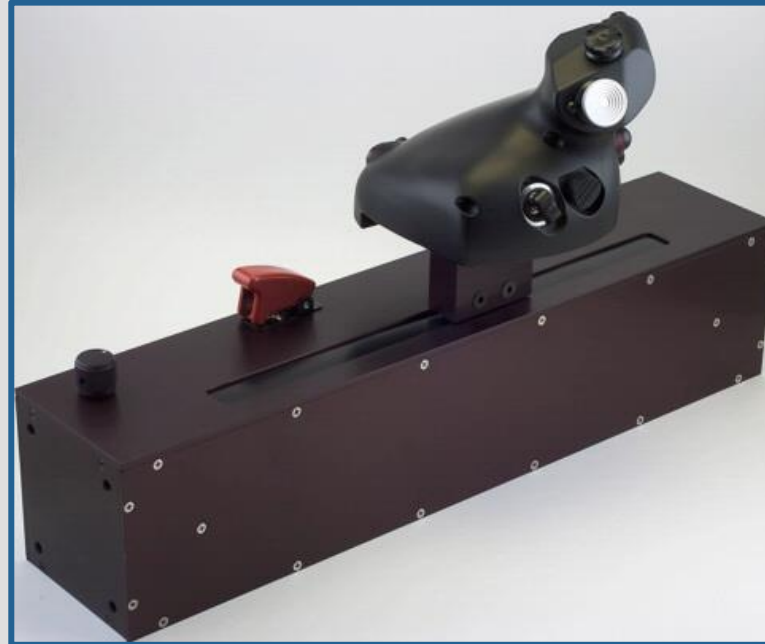


- ✦ Rudder Pedal System (RPS): Controls the jet rudders, nose wheel steering and rear wheel brakes
- ✦ Initially developed by a previous senior design team, we will integrate this RPS with minor modification

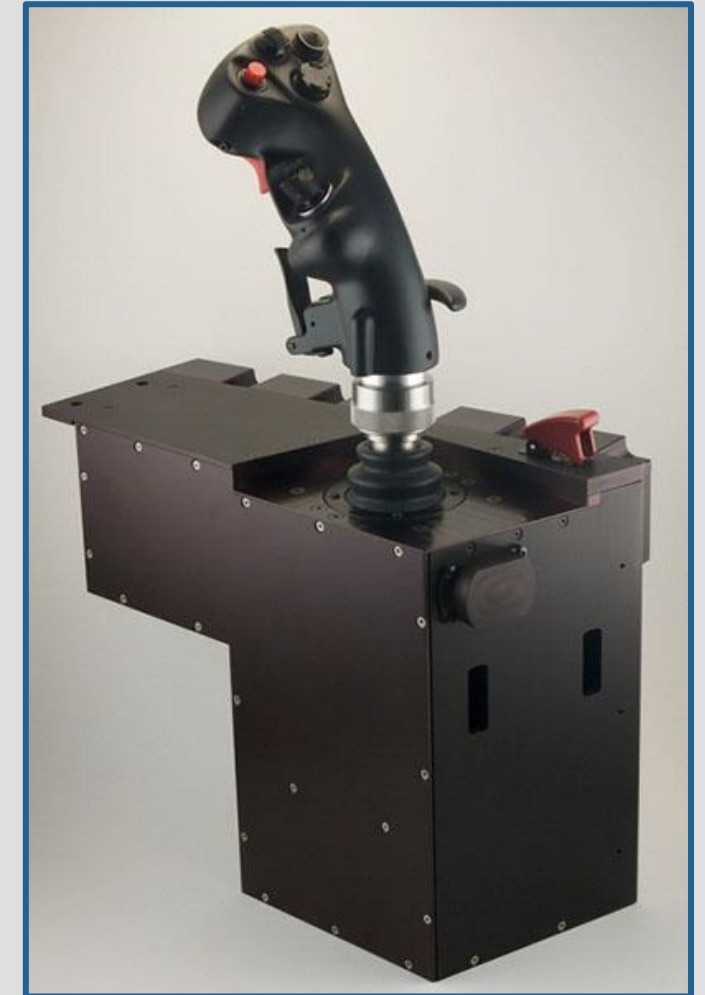
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HOTAS System

- ✈️ HOTAS: Hands on Throttle and Stick
- ✈️ Throttle: Controls the thrust from the jet engine
- ✈️ Stick: Controls the pitch and roll axes of the aircraft
- ✈️ Aspects of the HOTAS from previous senior design team will be incorporated in our version



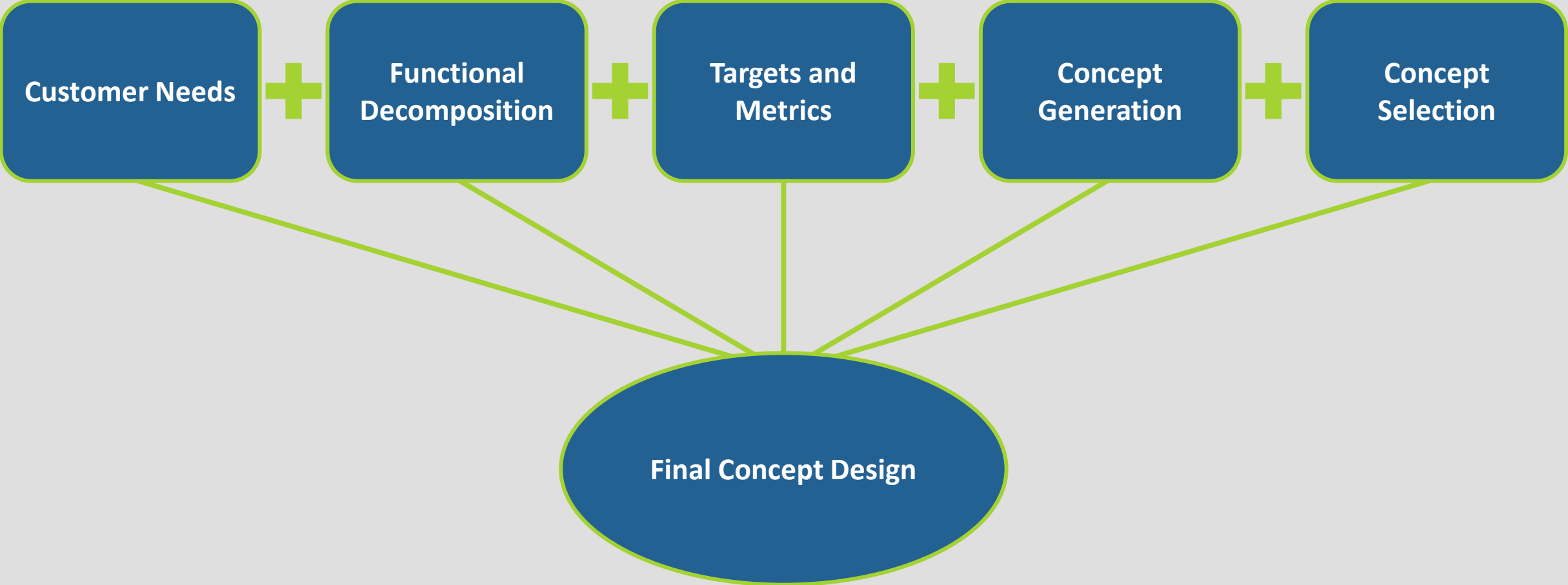
Throttle



Stick

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Last Semester

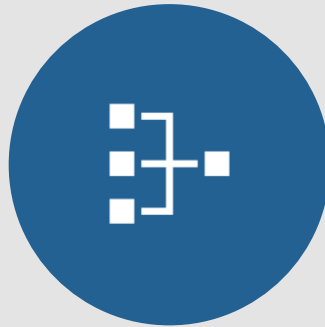


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Key Goals



Create finished,
working prototype



Integrate physical
sub-systems into the
simulation software



Keep
manufacturing
costs low



Design for use in
desktop or cockpit
training models

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Flight Control Functions

Pilot Interface

- ✈ Controls closely mimic F-35 look and feel
- ✈ Mechanic parts will withstand repeated use

Communicate to Software

- ✈ Controller position awareness
- ✈ Negligible input delay
- ✈ Inputs accurately affect simulated jet



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Critical Targets

Cost

Each new sub-system less than \$1000

Latency

No more than 20ms delay from input

Compatibility

3D printed cockpit and standard desk

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Additional Targets

Individual
Component < 35
pounds

Joystick deflection
13 degrees in all
directions

Throttle travel 6
inches

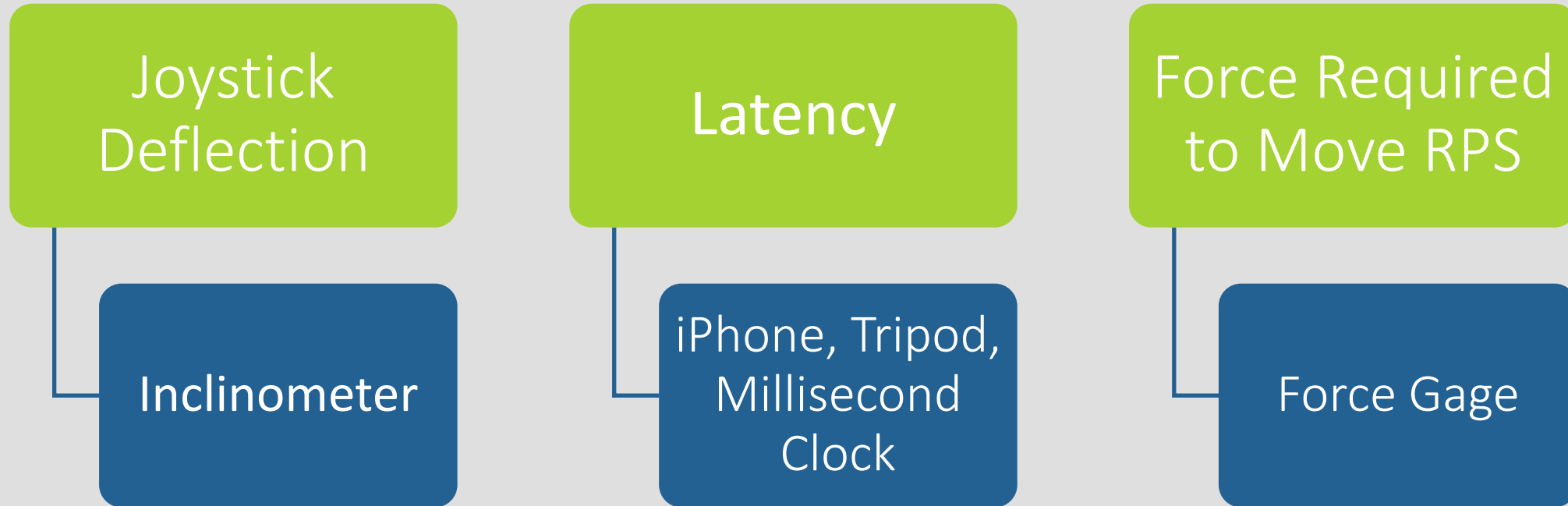
Operates 1 hour
without defect

No more than 15
lbf required to
move RPS

HOTAS withstands
applied 7.5 lbf

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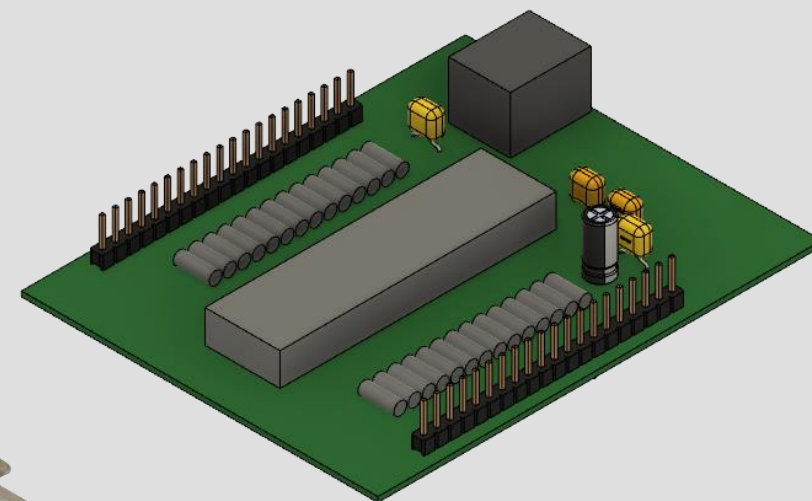
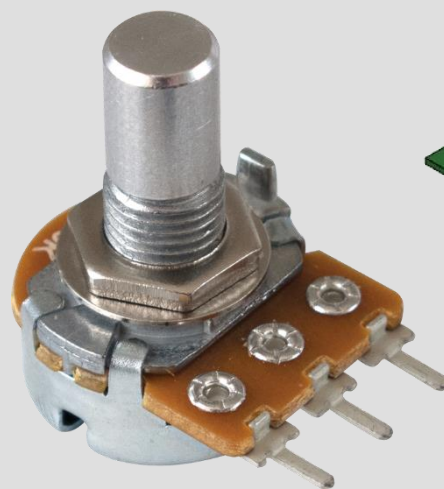
Testing and Validation Plans



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Final Design Selection

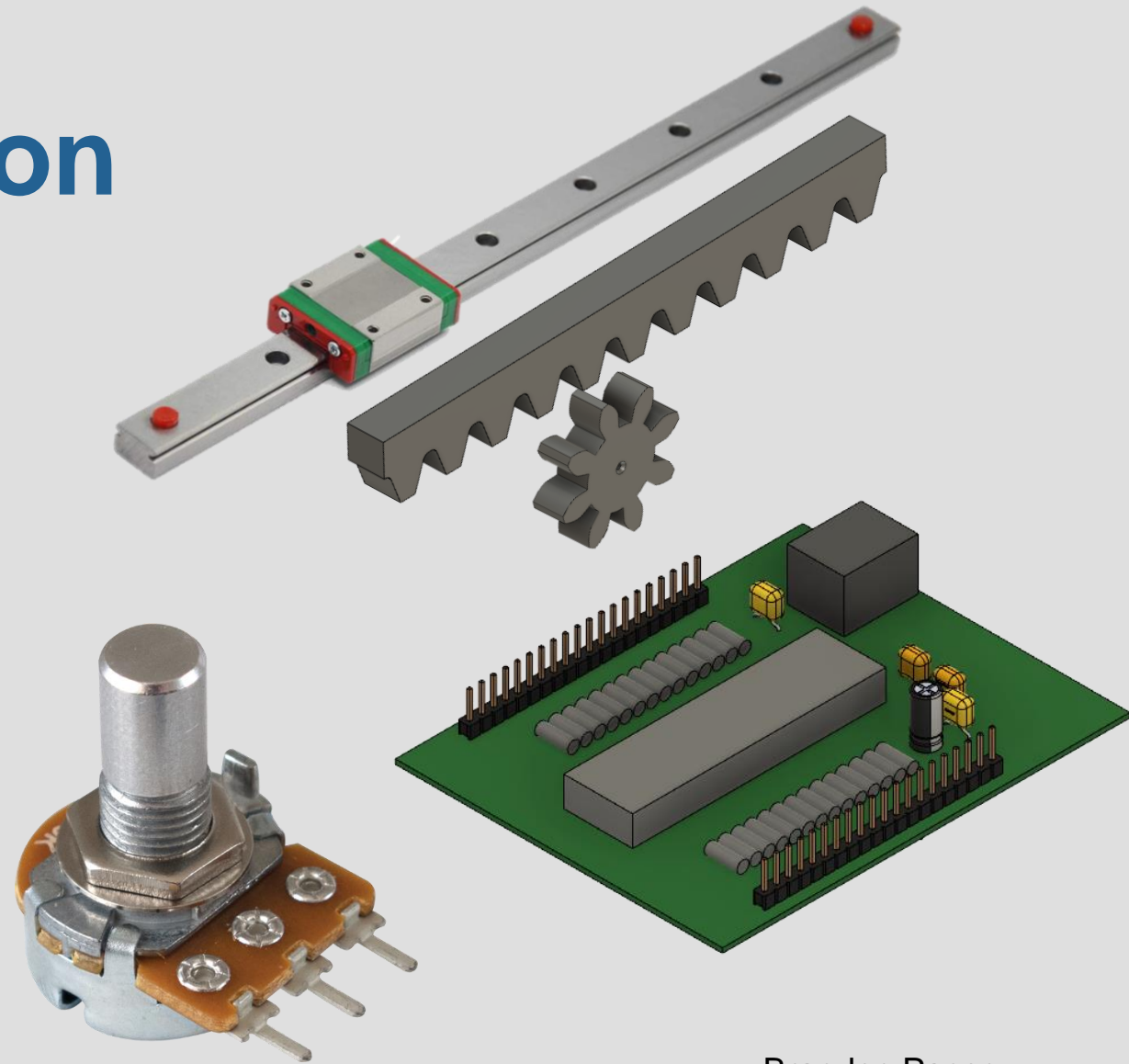
- ✈ Stick: 2-axis gimbal, rotary sensors, custom USB microcontroller
- ✈ Throttle: linear square rail, rack and pinion with rotary sensor, custom USB microcontroller
- ✈ Rudder Pedal System: updated rotary sensors, custom USB microcontroller



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Final Design Selection

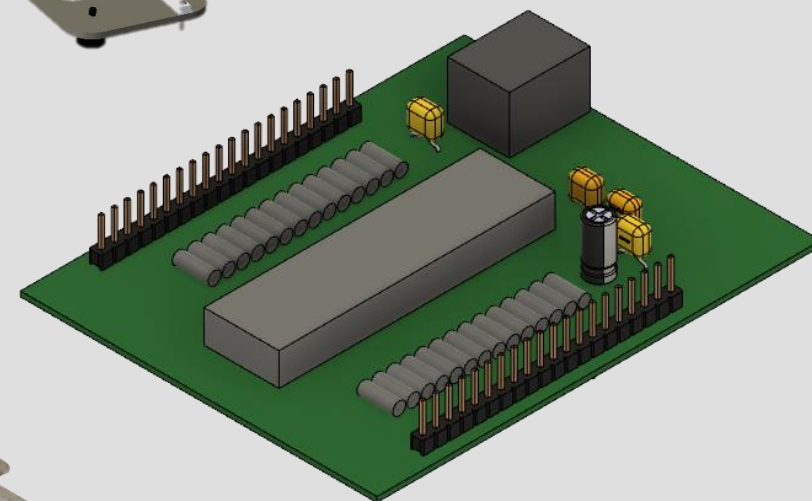
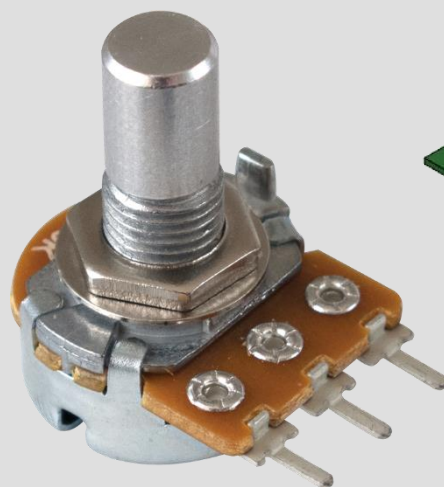
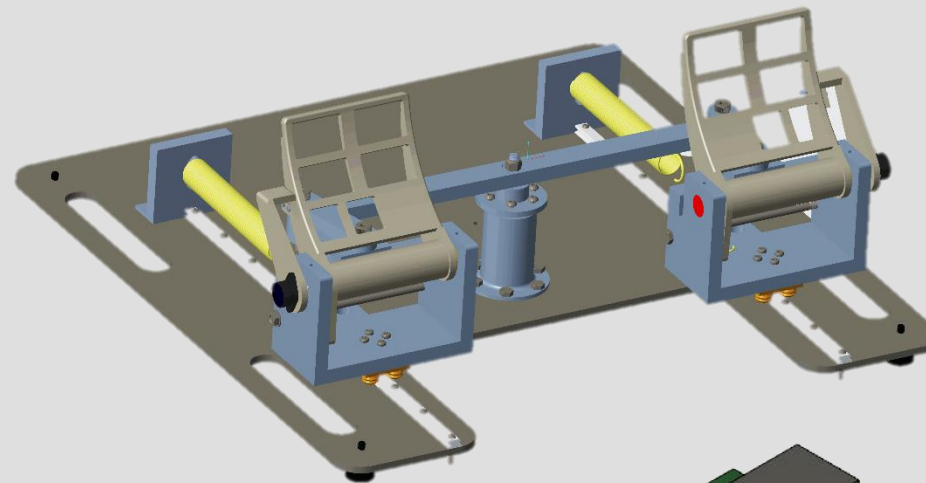
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Final Design Selection

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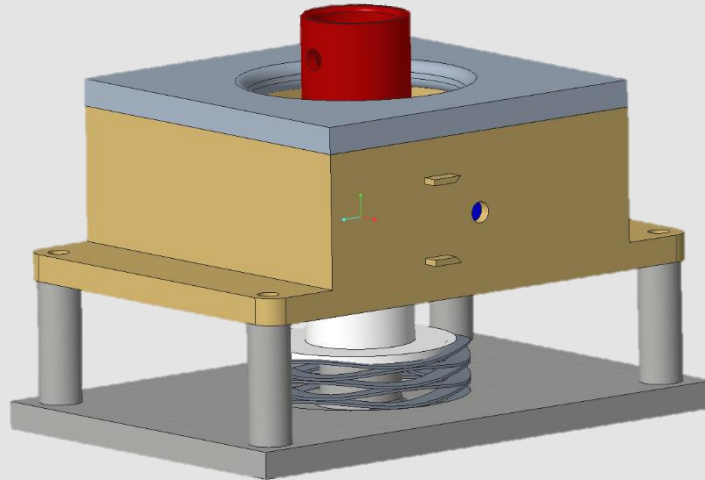


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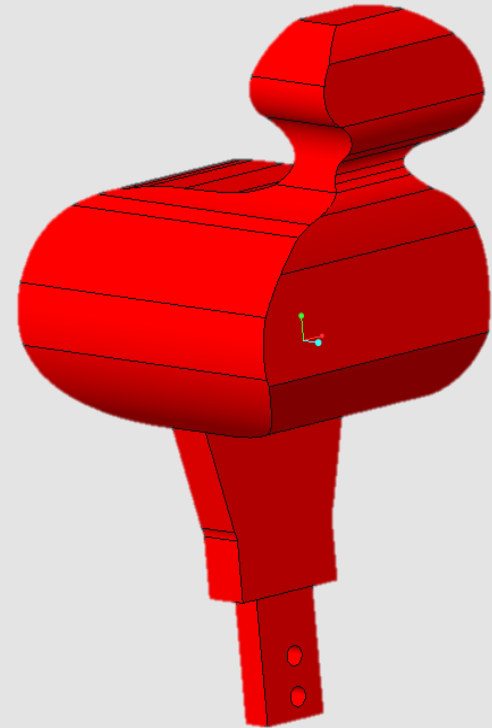
Current CAD Designs



Stick



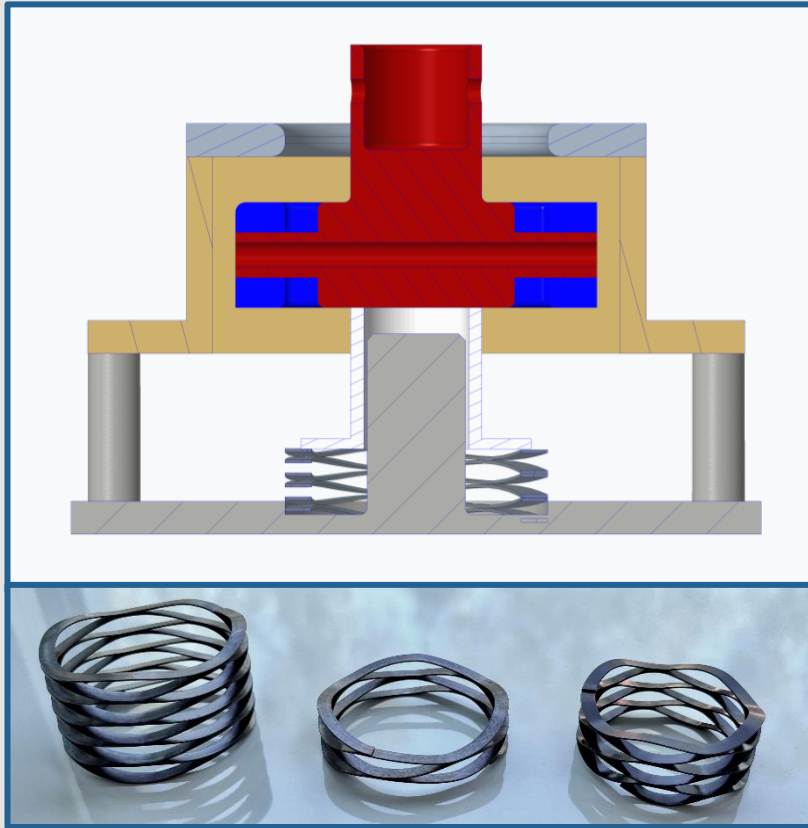
Joystick Gimbal



Throttle

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Update to Joystick Mechanism

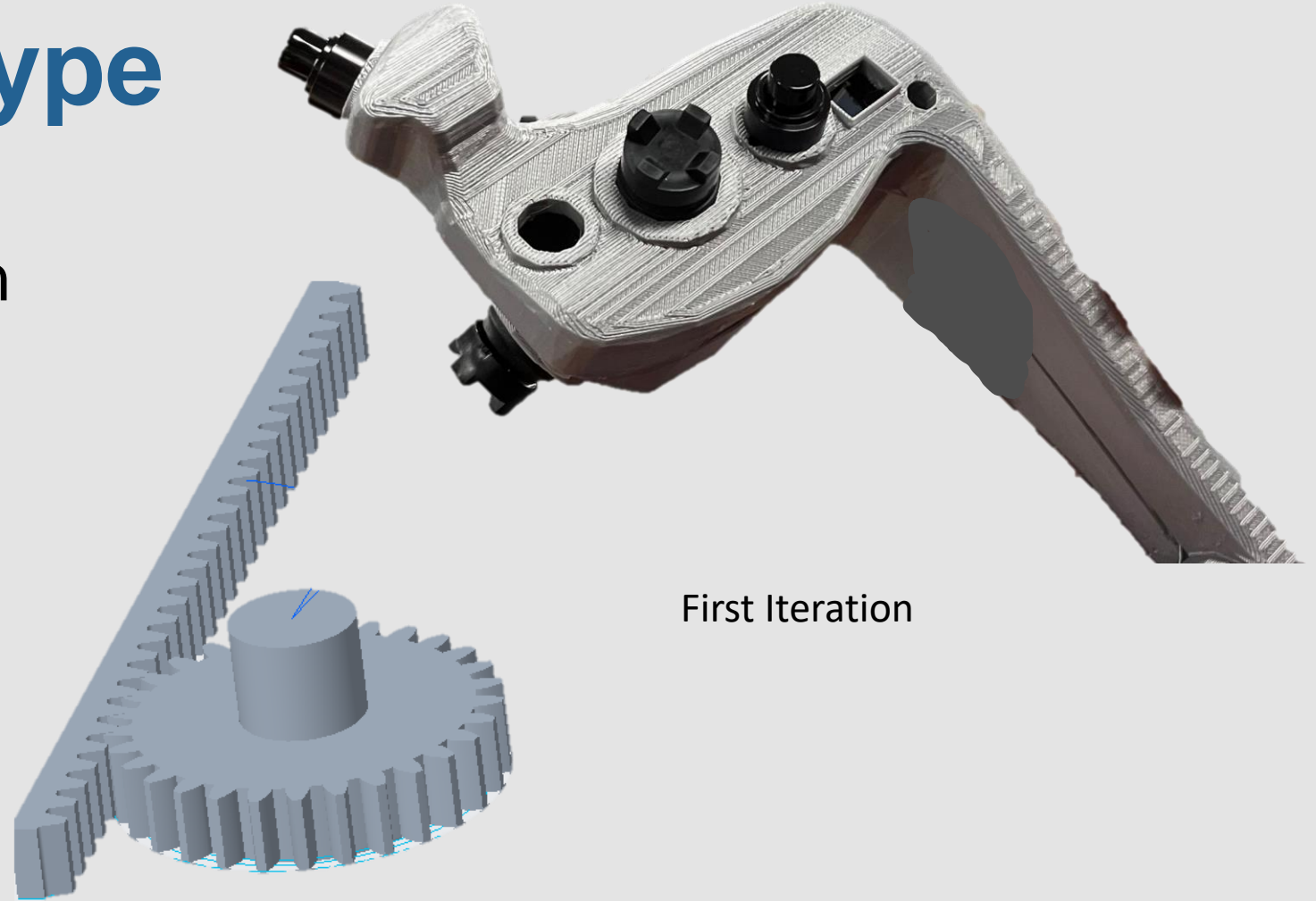


- ✦ Adjustable tension configuration considered.
- ✦ Wave spring now implemented.
- ✦ Gimbal geometry modified for potentiometers selected.

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Throttle Prototype

- ✈ Utilized Rack and Pinion to sense displacement
- ✈ Redesigned handle to conform to Naval Air Systems Command (NAVAIR) button mapping

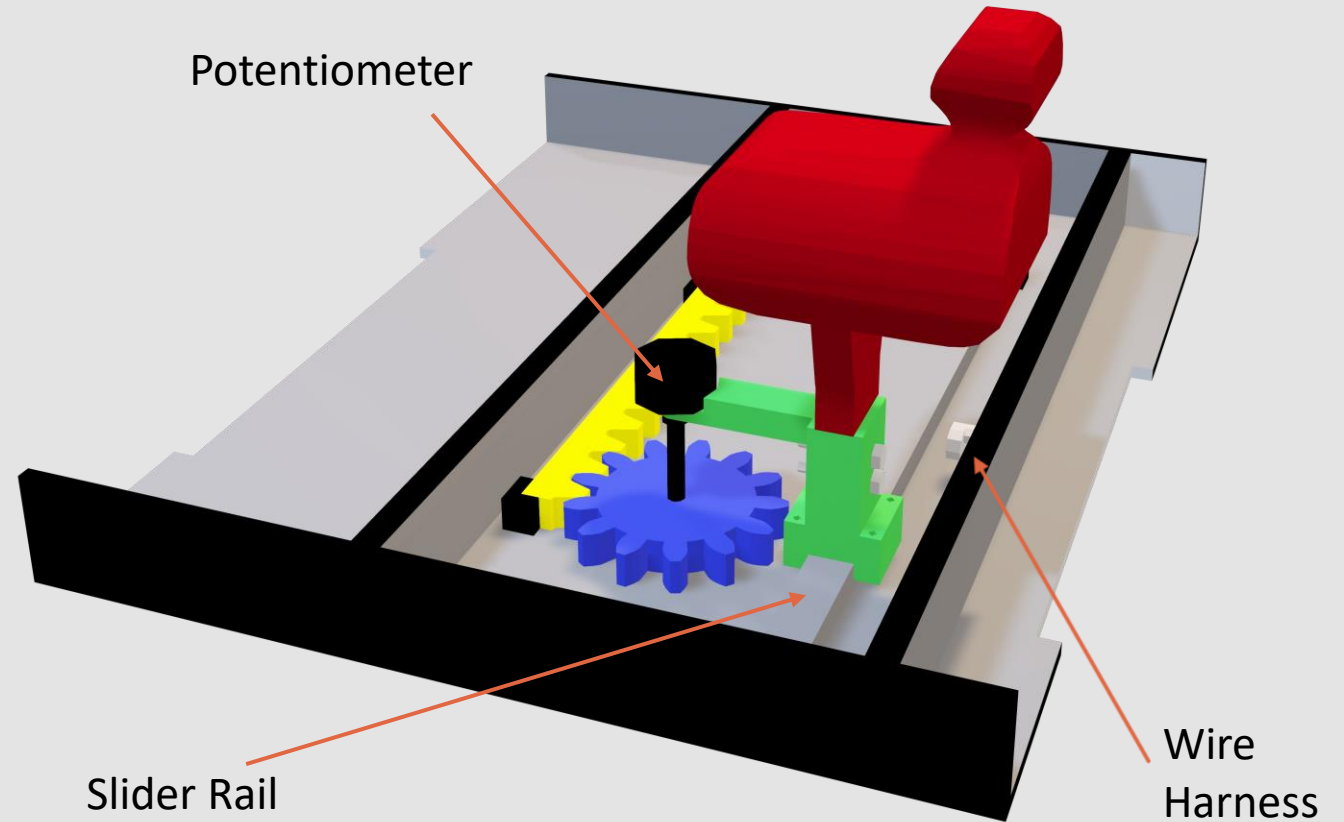


First Iteration

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Throttle Prototype

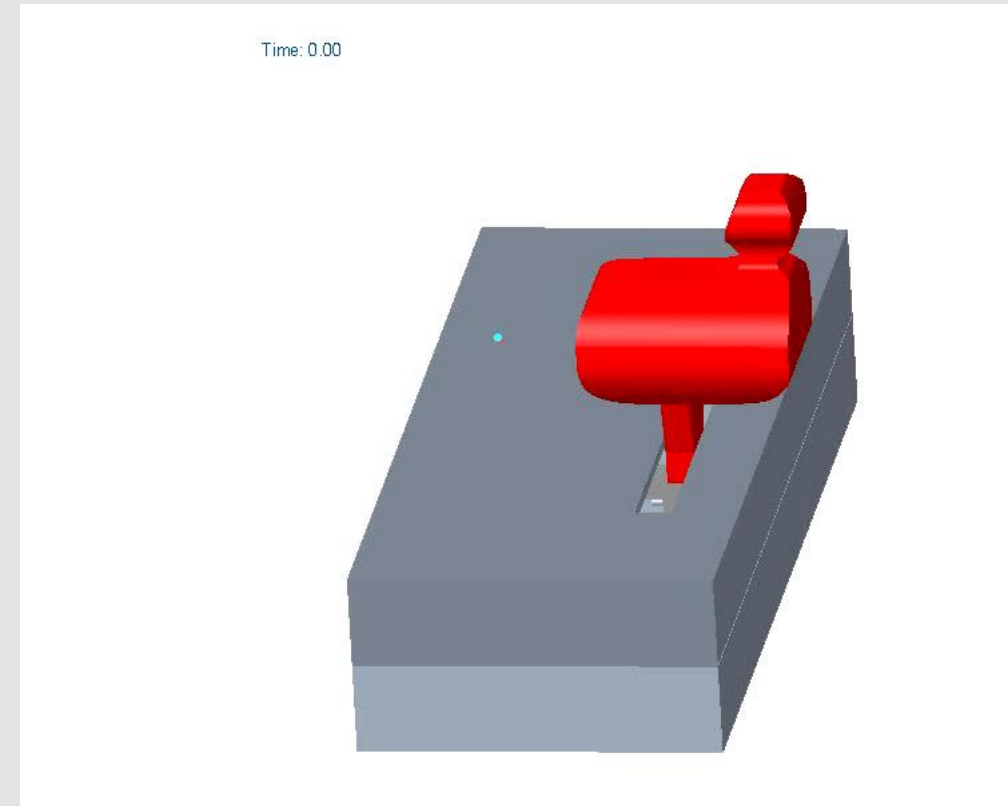
- ✈ First complete prototype has been drafted
- ✈ Kept rotary potentiometer due to budget
- ✈ Inner parts are being printed; outer shell is being revised



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Throttle Prototype

- ✈ Handle needs to be hollowed out and extruded for button placement
- ✈ Handle needs an updated design for negating misalignment errors under load



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Software Update

Integration

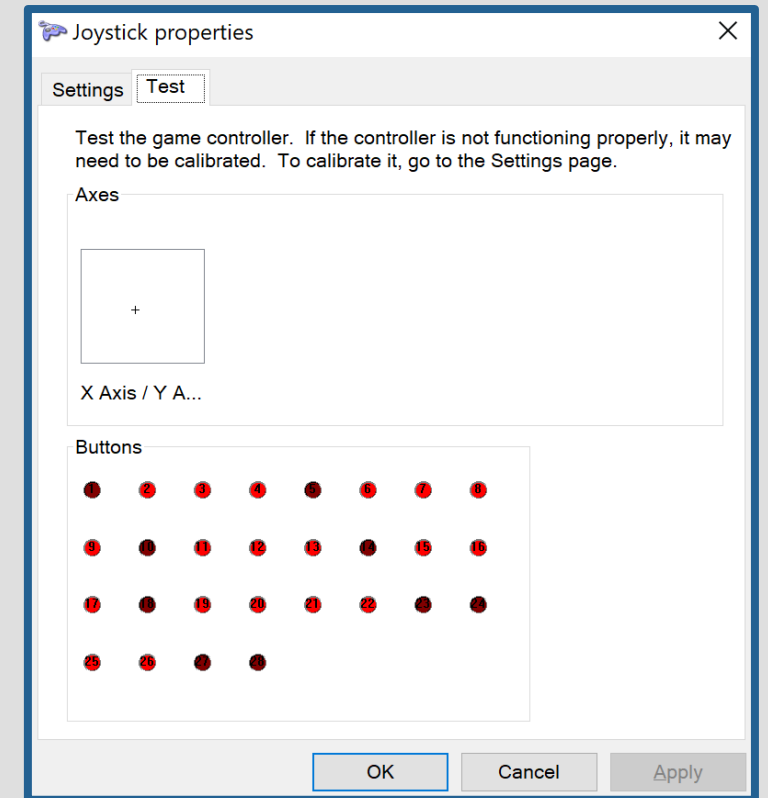
- ✦ Buttons are recognized by software
- ✦ Next function mapping

Firmware

- ✦ Over 90% complete

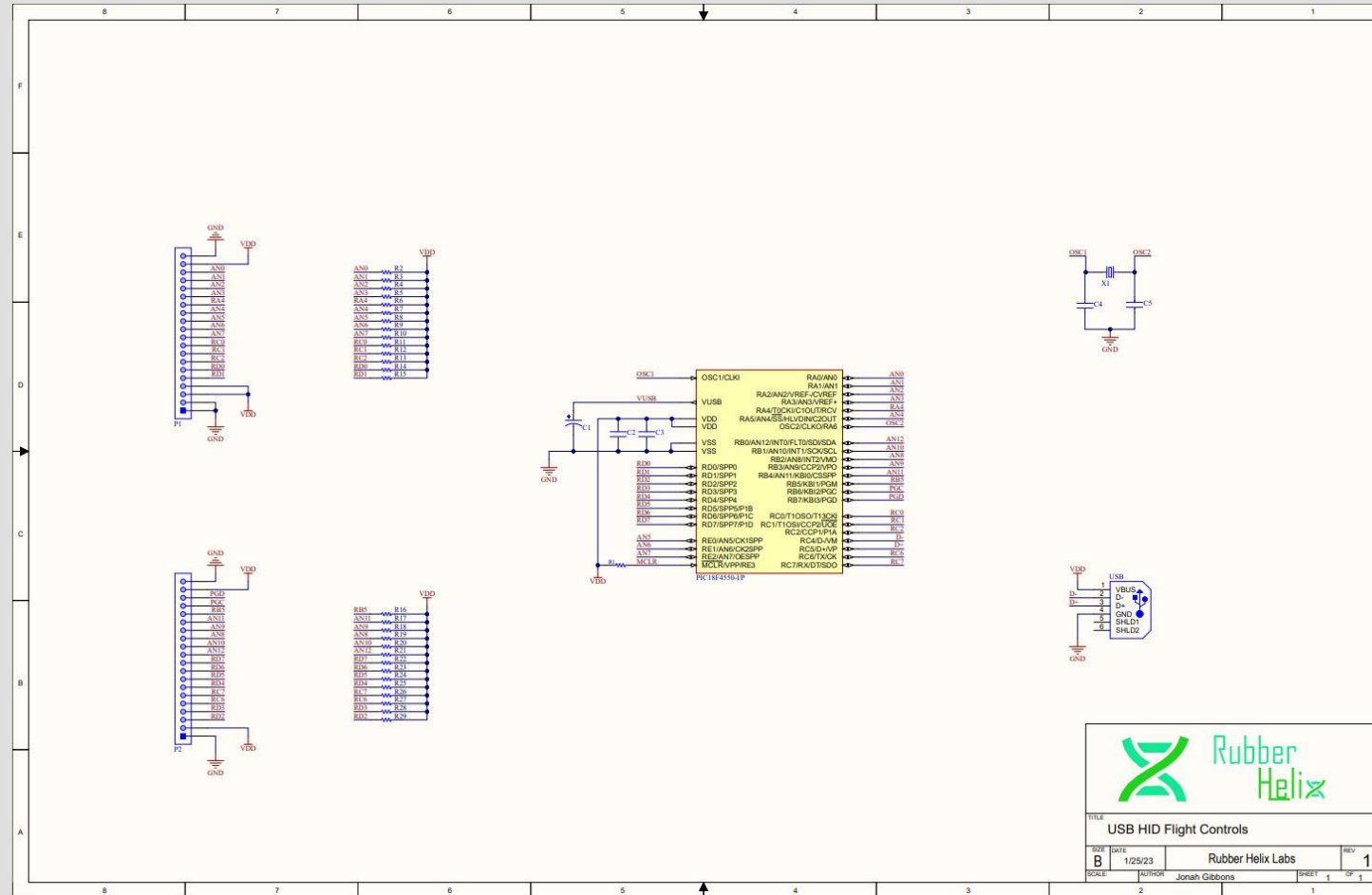
Latency

- ✦ Exceeds expectations
- ✦ Recognizes buttons immediately



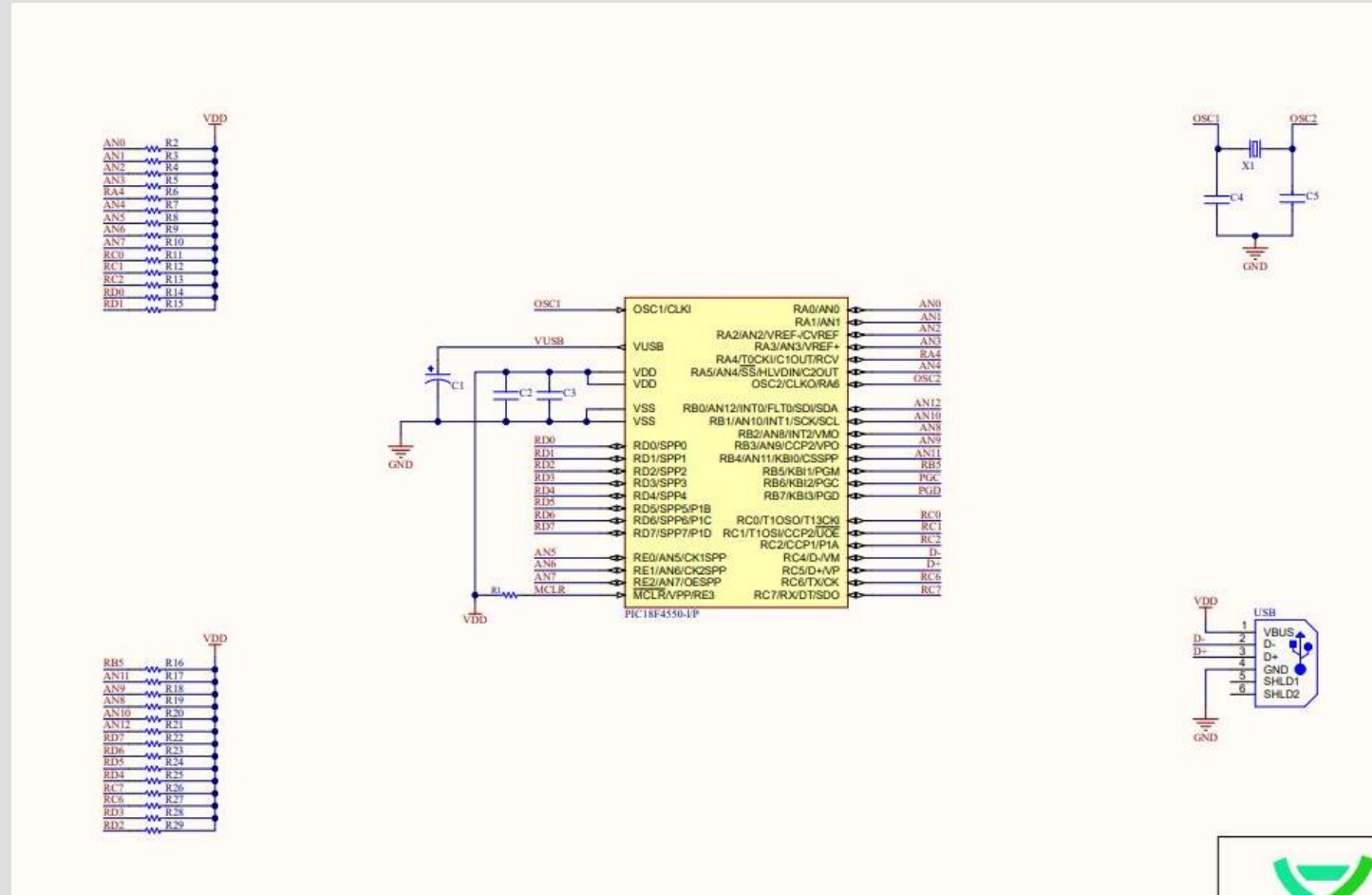
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Printed Circuit Board Schematic



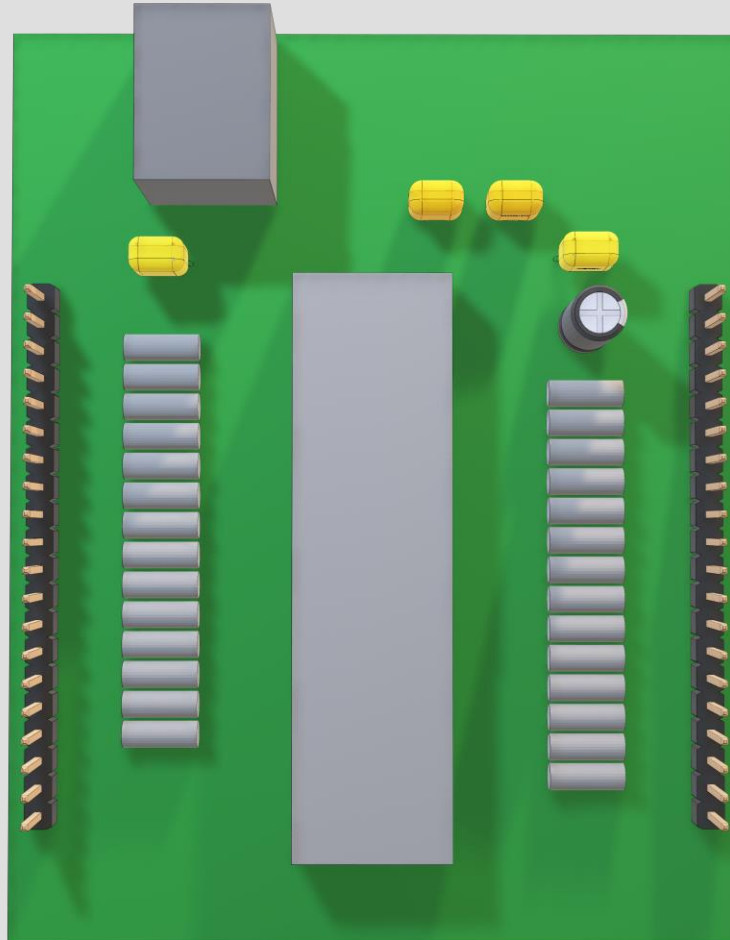
Laiken Kinsey

Printed Circuit Board Schematic



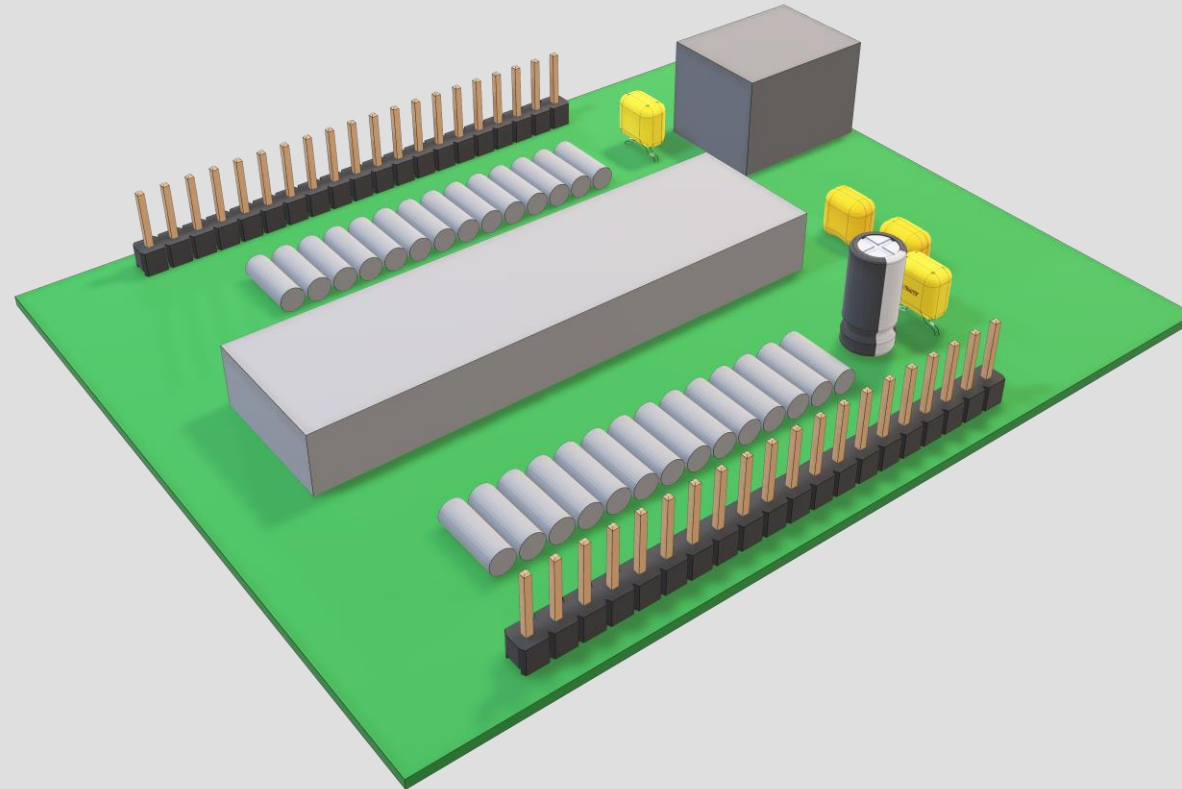
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Printed Circuit Board Model



Laiken Kinsey

Printed Circuit Board Model



Laiken Kinsey

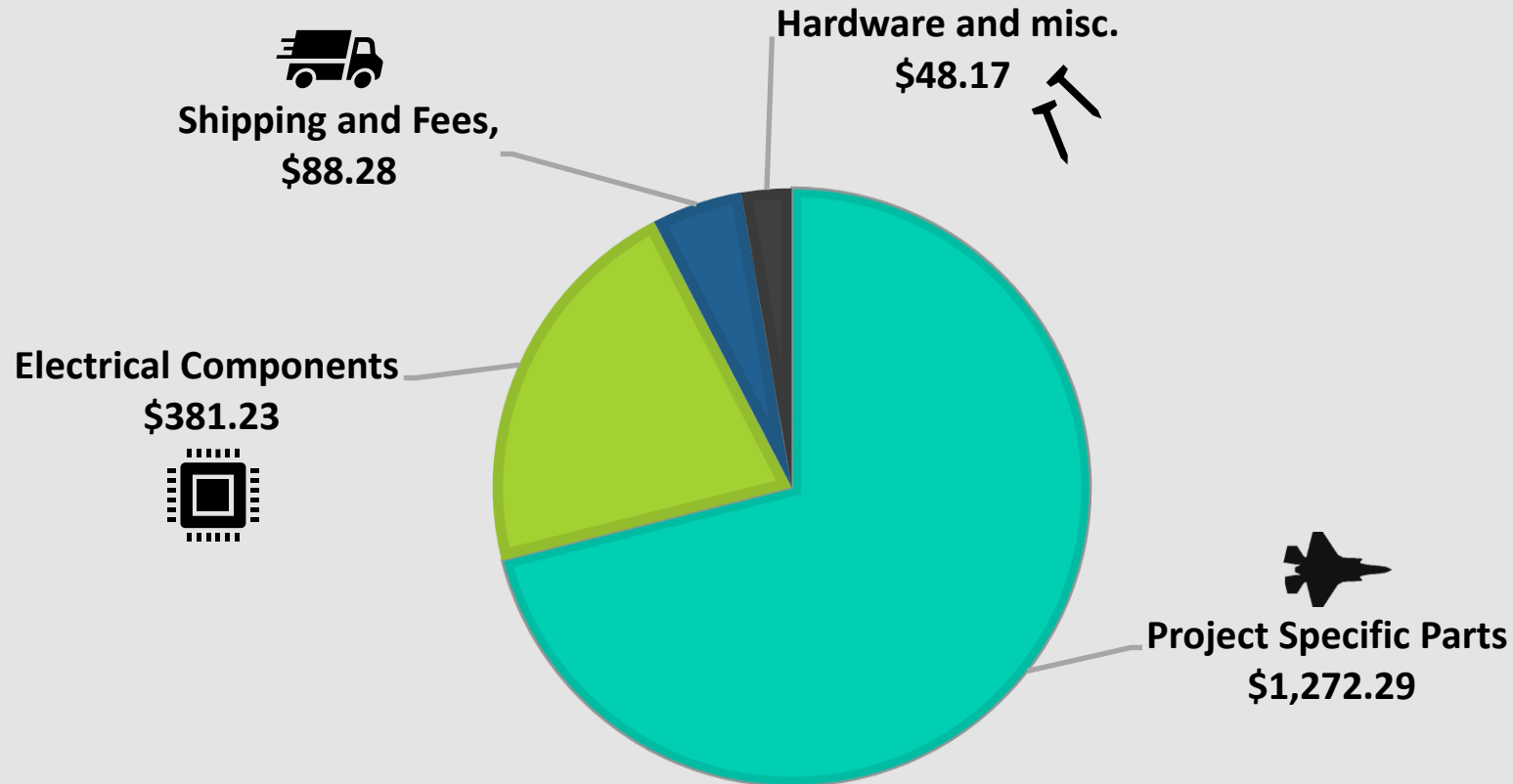
Materials Update

- ✦ Almost all parts have arrived.
 - ✦ The parts that have yet to come in are not crucial to assembly.
- ✦ We have used 62% of the budget on the first order and 28% on the second order.
- ✦ Currently, we are using parts already available to use for simple and non-specific applications.



Laiken Kinsey

Budget Update

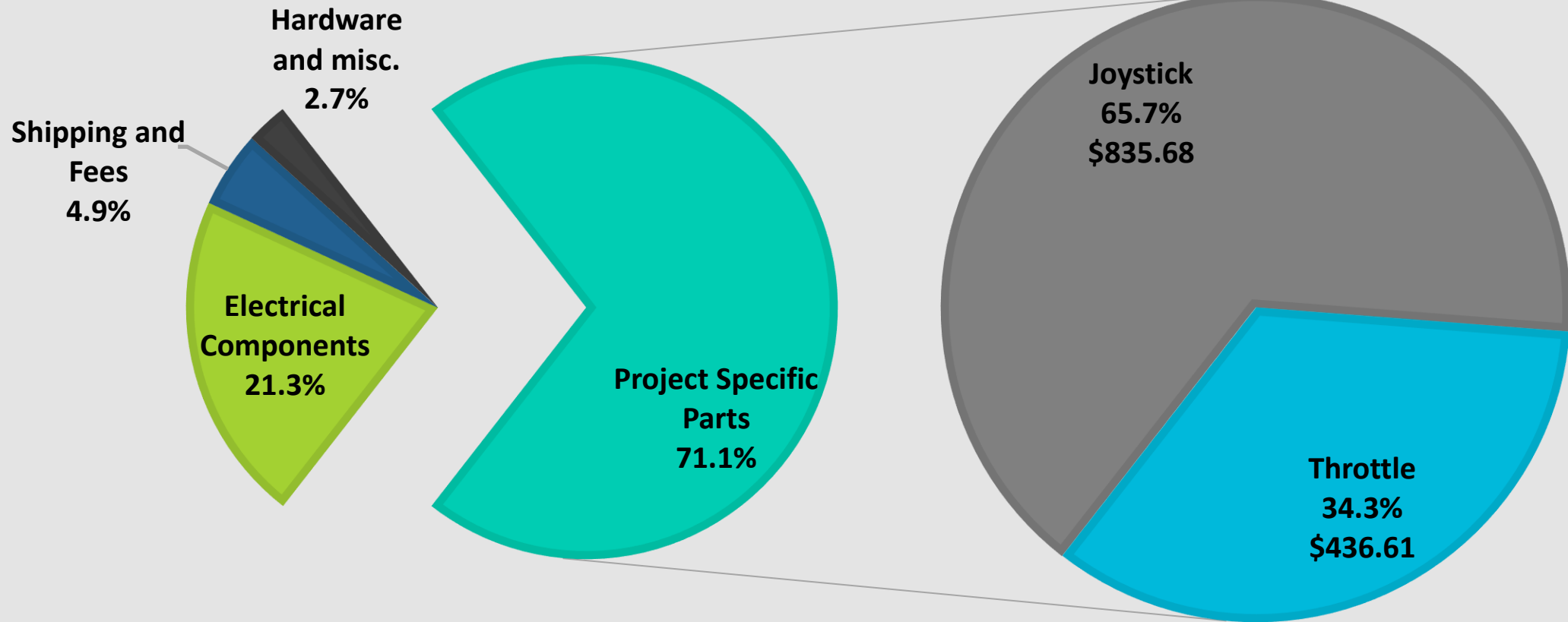


TOTAL COST TO DATE:
\$1789.97
89.5% OF OVERALL BUDGET

- Project Specific Parts : 71.1%
- Electrical Components : 21.3%
- Shipping and Fees : 4.9%
- Hardware and misc. : 2.7%

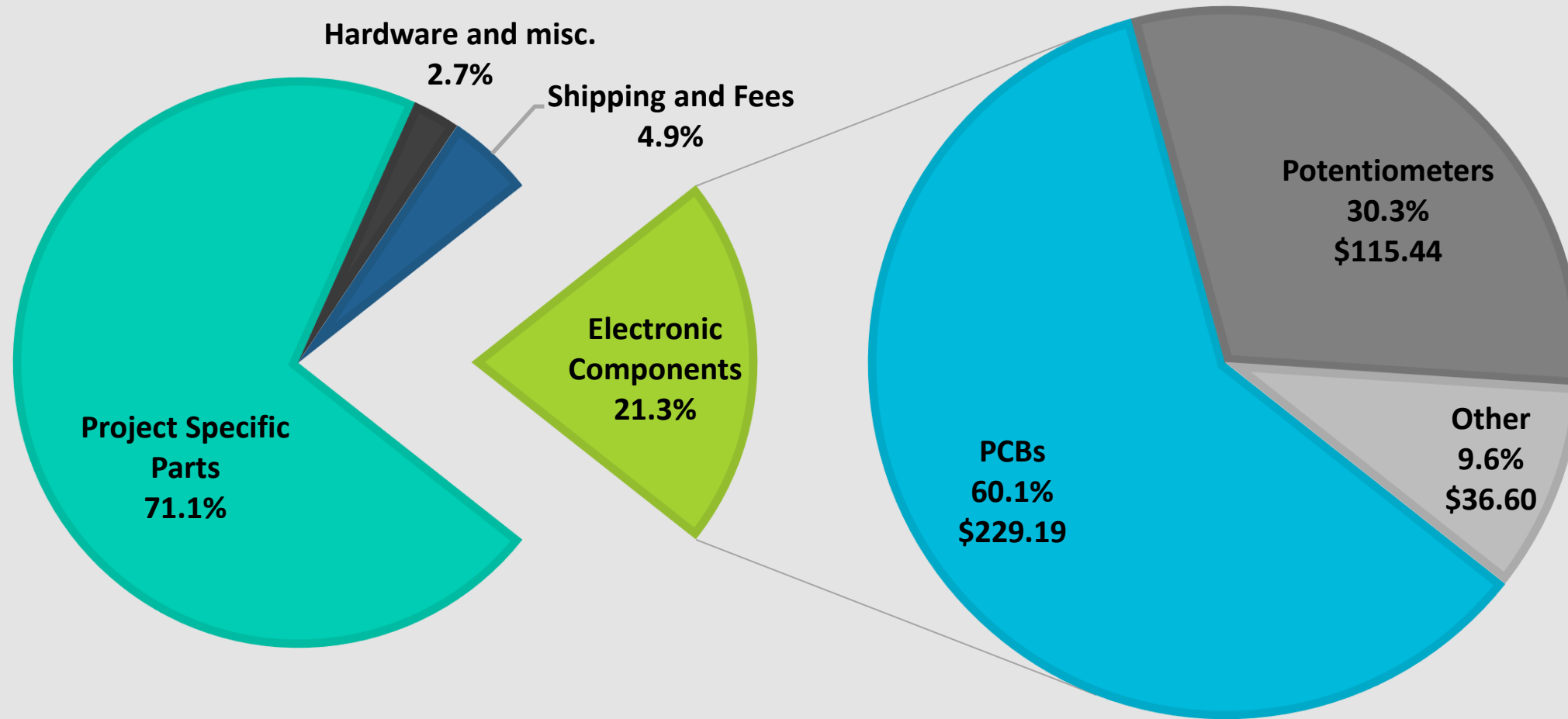
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Budget Update



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Budget Update



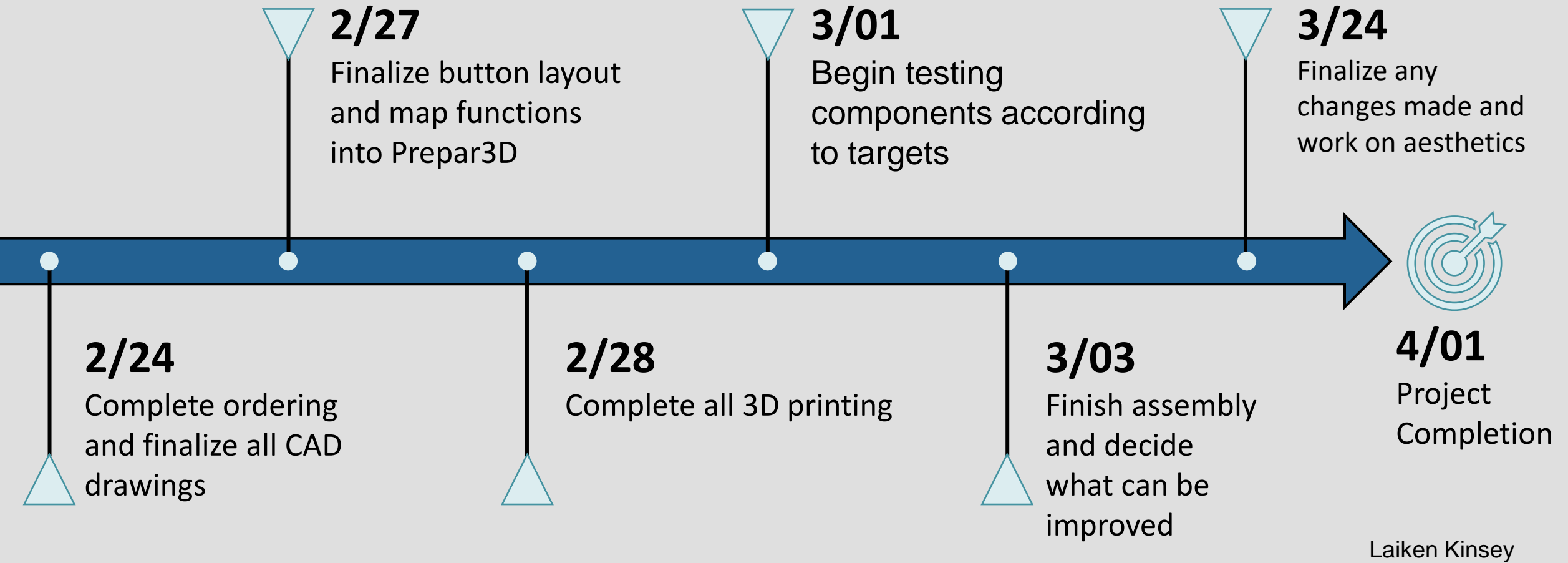
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Current Priorities



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Project Timeline



Questions?



Design Team



Sponsor



Objective



Background



Functions



Targets



Current CAD



Concept Selection



Project Timeline

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